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Analysis of the Frequency and Detectability of Objects Resembling Nuclear/Radiological Threats in Commercial Cargo

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ABSTRACT

The detection of smuggled nuclear/radiological materials or weapons in commercial cargo remains a severe technical challenge due to the complexity of the global cargo network, sources of normally occurring radiation, and the broad nature of the threat. This article presents an analysis of the physical constraints on the nature and detectability of nuclear and radiological threats, using 122,500 radiography images from a containerized cargo stream. This analysis suggests that existing radiography systems, in conjunction with passive monitoring, may offer stronger detection capabilities than previously realized and presents data on the distribution of material in stream-of-commerce cargo to inform the development of future technologies. **ARTICLE HISTORY** Received 6 December 2018 Accepted 1 July 2019

The detection of smuggled nuclear and radiological materials and weapons in maritime cargo containers remains an unsolved problem, despite focused research and political discussion on the issue that intensified significantly after the September 11, 2001, terrorist attacks and continues today. While cargo containers are not the only method that a terrorist could use to deliver the weapons or materials necessary for an attack, smuggling via maritime cargo is considered particularly threatening. Containers provide an ideal environment for concealing contraband, considering the volume of traffic to be monitored ($\sim 5 \times 10^4$ containers/day in the United States alone) and the fact that loading occurs overseas with inconsistent levels of security.¹

Estimates of the immediate economic costs of a nuclear explosion in a major United States port exceed \$1 trillion,² while even a much smaller-scale attack involving a radiological dispersal device (RDD, or "dirty

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bomb") could incur costs of up to tens of billions of dollars if trade is significantly disrupted.³ For these reasons, the United States government continues to pursue programs with the stated goal of inspecting 100% of U.S.bound cargo containers for the presence of nuclear weapons or special nuclear materials (SNM) required to make a nuclear weapon, prior to embarkation of the containers at foreign ports as mandated by the 9/11 Commission Act in 2007.⁴ Progress toward achieving this goal, however, has been hampered by the challenges of implementing systems in foreign ports with limited cooperation and financial support from local governments,⁵ a lack of clear and effective goals for development of technological solutions,⁶ and reluctance from shippers and port operators to implement inspection regimes that delay shipments or incur additional shipping costs.⁷

A number of techniques have been proposed for the detection of smuggled nuclear materials and weapons, although only two main classes of systems have been widely deployed: passive radiation detectors and gamma/x-radiography scanners. Passive detectors, while capable of detecting a variety of threatening radioactive materials, may be defeated by surrounding the smuggled object with enough material ("shielding") to absorb the radiation before it leaves the container. Radiography of containers, which is capable of producing high resolution images of containers for both manual and automated inspection, has been widely deployed for a variety of security applications.⁸ Generally, however, radiography alone has been considered insufficient for the detection of nuclear and radiological threats due to a lack of specific signatures for such threats, even in dualenergy systems that provide limited material-type identification.⁹ This has led to considerable research efforts to develop systems that can produce specific signatures for SNM. Concepts for such systems have included the detection of prompt neutrons from photofission,¹⁰ nuclear resonance fluorescence,¹¹ and a variety of others.¹² Due to the novelty, complexity, and cost of these systems, none have been deployed widely.

Given the difficulty and costs of developing and deploying highly specific nuclear and radiological threat detection systems, it is worthwhile to examine the capabilities of the existing commercial systems (i.e., passive radiation detectors and gamma radiography systems) to determine the extent of their capabilities so as to prioritize future effort and spending in this area. Specifically, given that passive radiation scanning is capable of detecting many classes of unshielded nuclear/radiological threats¹³ and that the materials required to shield an object from detection will be apparent in a radiograph,¹⁴ the question arises as to whether objects in cargo resembling threats (according to their signatures in these systems) are sufficiently rare so as to permit an interdiction system relying primarily on these existing technologies. To address this question, this analysis characterizes the

relevant nuclear and radiological smuggling threats and examines data from radiographic images of 122,500 stream-of-commerce cargo containers to determine the frequency of objects in the cargo which appear consistent with nuclear/radiological threats. The radiography system was modeled to allow prediction of the radiographic appearance of typical nuclear/radiological threats in terms of their effective size and density. The entire image set was then analyzed to determine the frequency of such objects. Assuming that the cargo stream contained none of the objects under consideration, the determined frequency amounts to the false alarm rate of an interdiction system that employs the methods of this analysis. It was found that, in this container stream, radiography can distinguish a large class of relevant threats with a false positive rate of $\leq 2\%$.

Classifying relevant nuclear and radiological threats

This analysis utilizes the fact that nuclear materials are typically characterized by two key characteristics: high density ($\rho \ge 18 \text{ g/cm}^3$) and high atomic numbers ($Z_U = 92$, $Z_{Pu} = 94$). Similarly, due to the necessarily high level of radioactivity of an effective RDD, any RDD that successfully evades passive detection will likely require significant amounts of dense, high-Zshielding or a combination of low- and high-Z shielding to capture neutron radiation.¹⁵ While an ideal system would detect even trace amounts of material present in a container, the large size of containers and high volume of cargo traffic would likely make such a system prohibitively costly and disruptive to port logistics. Thus, it is necessary to set reasonable detection goals and to properly assess the capabilities of existing and proposed systems of reaching these goals by comparison to data from actual stream-of-commerce containers. The two main classes of threats and their passive detectability are discussed here to establish criteria for the analysis of the image set.

Nuclear devices and special nuclear materials

The detection of an assembled, detonable nuclear warhead in a cargo container is clearly a minimum requirement of any interdiction system, but detection of smuggling of smaller quantities of highly enriched uranium (HEU), weapons-grade plutonium (WGPu), or other SNM intended for incorporation into weapons is also highly desirable. While it is generally considered that significant samples of WGPu are detectable by passive radiation monitors due to their strong fission neutron signature (or otherwise would be surrounded by very significant shielding), HEU produces very little passive radiation that would be likely to reach detectors.¹⁶ Thus, it is important to consider how assembled fission devices would appear in a radiograph (since these represent the minimum assembly required for nuclear detonation) as well as smaller samples of SNM alone (especially in the case of HEU). Due to the nature of SNM, these samples are still most likely to appear as anomalous dense regions in radiographs. Previous efforts have used 100 cm^3 (~2 kg) as a detection goal,¹⁷ which is used as a lower-bound test case in this analysis. Ultimately, the lower thresholds for SNM detection should be informed by knowledge of the processes used to construct weapons, information regarding smuggling incidents,¹⁸ and information from data sets such as the one considered in this work.

Radiological dispersion devices and radioactive sources

Regarding the detection of a radiological dispersion device (or a radioactive sample that could be used in such a weapon), it is assumed in this work that currently deployed radiation portal monitors meet the specified standards.¹⁹ Under this assumption, any attempt to smuggle a quantity of radioactive material that poses and significant threat would require shielding to avoid detection by passive monitors. Since a strong radioactive source may be quite small,²⁰ shielding scenarios on the scale of centimeters must be considered, although a dispersal weapon such as a dirty bomb would likely be considerably larger and thus require commensurately more shielding. Thus, searches for RDDs are in effect equivalent to searches for the shielding that would be required to hide them from passive detection.

Occurrence of threat-resembling objects in radiographic images of a commercial cargo stream

Given the capabilities of passive radiation detection systems already in widespread use at ports, the problem of detecting nuclear and radiological threats is primarily the detection of objects with sufficiently low radioactivity to be evade detection in feasible passive scanning scenarios. Such a sample may have naturally low passive radioactivity (such as HEU) or be encased in shielding to mask the signal. As noted in the previous section, a smuggler seeking to conceal a highly radioactive (≥ 1 TBq) object using shielding must use significant amounts of material that will appear as large, dense regions in radiographic images. For threats in involving SNM, while the materials typically emit less radiation than RDD isotopes and thus may require less shielding to avoid passive detection, a substantial quantity of SNM will also appear as a dense region in a radiograph. Since radiographic systems fundamentally measure the attenuation of a beam due to the material in a container as a 2-D function of position, they are naturally suited for identifying objects by these parameters.

While utilizing radiography to search for dense objects has been proposed previously as a mechanism for searching for nuclear and radiological threats in cargo,²¹ such a technique is feasible only if objects of the relevant densities and sizes are sufficiently rare in radiographs so as to not produce a large number of false alarms. To avoid disruption of the flow of containers in ports, cargo security schemes have typically sought to flag $\leq 2\%$ of containers as containing items consistent with threats.²² Additional inspection and/or intelligence information may provide more leeway, but likely at most a few percent of containers can feasibly be flagged for further inspection. Previous data have provided information regarding the mean density of entire cargo containers,²³ but such studies underestimate the occurrence of dense cargoes (due to the averaging of dense regions with empty regions) and provide no information regarding the frequency of contiguous dense regions that resemble threats. This analysis characterizes the expected appearance of threatening nuclear/radiological objects in radiographs and examines a large set of high-resolution radiographic images from a 6 MeV endpoint bremsstrahlung imaging system to identify the frequency of such objects. If such objects are sufficiently rare, then, in conjunction with passive scanning to detect unshielded threats, radiography is likely sufficient for identifying important classes of nuclear/radiological threats.

Image data set

The analysis was conducted on a set of 122,500 radiographs of intermodal cargo containers, approximately evenly split between 20-foot and 40-foot containers, produced by a Rapiscan Eagle R60[®] scanner²⁴ examining rail car-borne containers entering a European port. The container stream represented a diverse array of cargo, and approximately 20% of the containers were empty.²⁵ Each image consisted of a two-dimensional array of 16-bit pixels representing the integrated energy transmission (measured by CdWO₄ detectors) of a 6 MeV endpoint bremsstrahlung beam through the cargo relative to the open beam.²⁶ Each pixel represented an approximately 5×5 mm region on the mid-plane of the container transverse to the beam.²⁷

This image set was previously analyzed in the context of using machine learning techniques to identify complex objects such as vehicles in cargo image.²⁸ The analysis was conducted on images preprocessed according to the methods discussed in Section 7.2.2 of Rogers,²⁹ which trimmed the images to remove blank space around the containers and corrected for known system artifacts in the images. Additionally, for this analysis the images were further trimmed to remove any portion of the rail car present in the image. Any images with resulting sizes inconsistent with the

expected container sizes or otherwise anomalous data were excluded from the analysis. These images constituted \sim 3.1% of the available images and are not counted in the 122,500 total.

Analysis

The analysis sought to test the hypothesis that radiological and nuclear threats may be detected in radiographic images of cargo containers by identifying them by their anomalous size and density relative to common cargo. To accomplish this, the radiographic system was modeled so as to allow the simulation of images of threatening objects and to characterize their appearance in images. The cargo images were analyzed for the presence of contiguous dense regions and the frequency of regions matching the parameters of the simulated threats was examined. If the occurrence of threat-like objects in the cargo stream is sufficiently small ($\leq 2\%$), then radiography provides a stronger tool for detecting nuclear/radiological threats than previously has been appreciated. Additionally, a number of other results regarding the distribution and density of materials in containers follow from the analysis, which provide useful data for various studies in cargo threat detection.

Radiographic system model

Due to the high intensity of photons in a bremsstrahlung radiography system, the detectors are operated in charge summing mode (in which the signal is roughly proportional to the total energy deposited in a detector over an integration time window), rather than counting mode (in which individual photons and their deposited energies are detected). The fundamental quantity measured by the system for a given material in the beam is the transmission ratio (scaled to the 16-bit dynamic range of the detectors for the Eagle R60[®] system)

$$T_{\rm mat} = (2^{16} - 1) \frac{Q_{\rm mat}}{Q_{\rm air}},$$
 (1)

where Q_{mat} is the charge sum for a fixed period with the material in the beam and Q_{air} is the sum for an equivalent period with no intervening material. In practice, radiographic systems like the one described in this study have dynamic calibration mechanisms to account for variations in the beam and detectors to ensure proper normalization between Q_{mat} and Q_{air} .³⁰ The detected charge sum may be modeled as

$$Q = C \sum_{j} E_{j} (\mathcal{DM}\vec{b})_{j} + N(Q), \qquad (2)$$

where C is a proportionality constant, \vec{b} is a vector representing a histogram of the bremsstrahlung beam spectrum as a function of photon energy (with bin energies E_j), \mathcal{M} is the matrix representing the effect of the material on the transmitted beam (such that $\mathcal{M}\vec{b}$ is the transmitted spectrum histogram), \mathcal{D} is the detector response matrix (such that $\mathcal{D}\mathcal{M}\vec{b}$ would be the detected spectrum histogram if the detector could be operated in photon counting mode), and N(Q) is a noise term that, in general, depends on Q. Models for each of these quantities for the system and a full range of materials were developed using simulations based on the Geant4 framework³¹ and NIST photon cross section data,³² the details of which are described in the first section of the Appendix. Since this analysis examines only average behavior over many pixels, the noise term (which may arise from counting statistics, electronics noise, etc.) is treated as a net effect on the reconstructed value of T_{mat} as described in the section of Appendix A addressing the uncertainty on the transmission measurement.

While information regarding the materials and their arrangement was not available for the container image data set to allow direct comparison of the model to images of objects in the images, the model was validated against known steel features of the containers (e.g., the known average thickness of the steel container walls) and the empirically determined parameters of the Rapiscan Eagle R60[®] system (e.g., the quoted upper bound on the system's effective penetration in cm-steel equivalent).³³ The details of these comparisons are described in the section of Appendix A assessing the validity of the model. While only steel container features were available for direct comparison between the container radiography data and the model, both the NIST photon cross section data³⁴ and the Geant4 photon interaction models used for this analysis³⁵ have been validated as both mutually consistent and consistent with data across all relevant materials. Given the relative simplicity of the radiography system (i.e., in that the beam was well collimated and the detector pixels small to heavily suppress non-direct beam photons from reaching the detectors), it can be reasonably assumed that the model performs well for all materials. As discussed in the final section, future work would be strengthened by the availability of data that would allow direct comparison of radiography system models to imaged objects.

Rather than work with the transmission ratio T, it is customary in radiography to compare cargoes of different materials to the equivalent thickness of steel that would result in the same value of T. Using the previously mentioned models, a look-up table was created for each elemental material to map amounts of a given material to centimeters of steel at equivalent T. This conversion was used to compute the effective object sizes in Table 1 and is utilized for all further discussions of imaged cargo. For a more detailed discussion of cargo radiography, see Chen.³⁶

Object	Outer Radius (cm)	Threshold S (cm-steel)	r _{eff} (cm)	A _{eff} (cm ²)
100 cm ³ SNM	2.9	15.6	1.5	4
WGPu M _{crit}	4.5	21.2	2.1	10
HEU M _{crit}	8.5	25.6	7.5	166
WGPu model	21.0	25.6	9.6	272
HEU model	23.0	25.6	11.7	413
WGPu model (no tamper)	18.0	25.6	6.8	90
HEU model (no tamper)	20.0	23.7	6.5	27
3 cm Pb shell	11.5	21.2	9.8	69
6 cm Pb shell	14.5	25.6	12.6	321
9 cm Pb shell	17.5	25.6	16.0	765
HEU $M_{\rm crit}$ + 3 cm Pb	11.5	25.6	9.8	235

Table 1. Summary of the shielded and unshielded nuclear/radiological threats chosen as typical examples for this analysis and their expected radiographed sizes at the highest practical density threshold for each object.

See the discussion of "Dense Object Finding" in the text for the definitions of r_{eff} and A_{eff} . The outer radius of the full physical extent of each object is provided as a reference of the maximum possible reconstructed size of the object. The first three objects are spherical masses of SNM, the latter two of which are just below a critical mass.⁴¹ The second set consists of the prototypical nuclear weapon models described in Fetter et al. with both the full models described in Fetter⁴² and the same models without inclusion of the tungsten or depleted uranium tampers. Each lead shielding shell, the third set of objects, has an inner radius just large enough to contain the HEU critical mass. See Table B1 for the detailed composition of each model object.

Dense object finding

To measure the occurrence of dense objects in cargo and their sizes, each image was analyzed for contiguous regions exceeding given thresholds of steel equivalent thickness ranging from 11- to 30-cm steel equivalent. For each image and thickness threshold, the image was converted to a binary image of above/below threshold and the MATLAB® Image Processing Toolbox was used to identify all distinct 4-connected regions in the image above the threshold.³⁷ The image toolbox was used to determine several parameters for each region including the total number of pixels in the region, the geometric centroid, and the bounding box (smallest rectangle aligned to the image axes that contains the region). Each distinct 4-connected region was characterized by two parameters for comparison to the expected sizes of threat-like objects: $r_{\rm eff}$ and $A_{\rm eff}$. The effective radius $r_{\rm eff}$ was defined to be the radius of the largest circle centered at the geometric centroid of a region contained within the bounding box of the region (scaled to the effective pixel size along the transverse mid-plane of the container to convert to cm). The effective area $A_{\rm eff}$ was defined to be the total number of pixels above threshold in the region times the approximate cross-sectional area of a single pixel ($\sim 0.25 \text{ cm}^2$). The parameter r_{eff} works well for characterizing compact objects, like a small mass of SNM, while A_{eff} better represents the size of elongated objects. Note that under this definition, the image of an annular object will result in a value of $r_{\rm eff}$ comparable to the outer radius of the object but with a smaller $A_{\rm eff}$ than a filled-in circular image of the same radius.

The results of this analysis for a 20-foot container of palletized cargo at two different thresholds are shown in Figure 1 as an example representative of a cargo type that contains significant dense regions. Additionally, the figure includes an additional image in which a simulated fission device is inserted into the image and identified by the algorithm as a large dense region. In the figure, the circles represent the circle defining $r_{\rm eff}$ and the crosses mark the centroid and total extent of each region.

Characteristic test objects

For concreteness in the following discussion, it is useful to define several specific examples of potential smuggled objects. Since a spherical object minimizes the effective radiographed area from an arbitrary angle of a given amount of material, the example objects considered here are each spherically symmetric. While a smuggler could, in principle, machine material and pack a container so as to make an object thinner along the beam direction and thus appear less dense, this would be difficult or impossible in many scenarios. For example, the geometry of an assembled weapon is fixed, and changing the configuration of smuggled materials would increase the amount of shielding required to mask any passive radiation (making the object appear larger in the radiograph).

The considered objects, summarized in Table 1, were chosen so as to broadly represent three classes of objects: bare masses of SNM, assembled model warheads, and lead shields that could be used to mask a small sample of an RDD isotope or HEU. In the first category, near-critical masses of WGPu and HEU as well as a 100-cm³ mass of material were considered as scenarios in which material is shipped for incorporation into a weapon after delivery. The critical masses represent the scenario in which enough material is shipped at once (in theory) to create a weapon, while the 100 cm³ represents a smaller sample that has been the detection goal of past development efforts.³⁸ The second category models the model of the nuclear weapon models described in Fetter et al.³⁹ as prototypical representations of HEU and WGPu weapons. The warhead models originally described in Fetter et al. were designed so as to minimize the passive radiation signature of the warheads, and thus they included thick tamper layers consisting of either tungsten or depleted uranium that significantly increase their radiographic signatures. To account for this, versions of the models which do not include the tamper layer have also been analyzed, so as to approximate the case that is most difficult to detect via radiography (i.e., hollow shell assemblies of SNM with minimal additional material). Note that these devices represent only the essential components of a fission device (i.e., SNM, tamper, neutron reflector, and chemical explosives), and

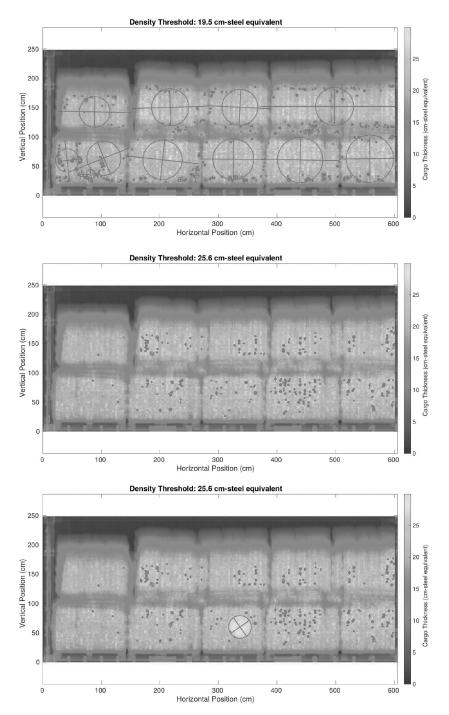


Figure 1. Sample images of a 20-foot container with palletized cargo two-high stacks for which the analysis described in the text has been performed to identify contiguous dense regions in the cargo. In the top figure the threshold is set to 19.5-cm steel equivalent, just below the average thickness of the pallet stacks (\sim 20.5-cm steel equivalent), and thus the algorithm identifies the individual pallets as the regions above threshold. In the middle image the threshold is set to 25.6 cm steel, the value used in this analysis to search for larger objects of interest such

thus a real assembled device would likely have additional components that would increase the apparent size of the object in a radiograph. The third category examines shielding scenarios that could mask small samples of either RDD isotopes or uranium up to a few inches of lead encasing a sphere of radius 8.5 cm (so as to fit the HEU critical sphere).⁴⁰ Note that any scenarios involving more shielding or shielding of larger objects would be necessarily easier to detect via these criteria. Table B1 presents the detailed composition of the test objects.

Applying the radiographic system model, the transmission of the beam through each of the test objects was simulated so as to produce simulated radiographic images of each object in the absence of any additional material. As described in Appendix A, the simulated images were produced with the same pixel size as the data (assuming placement in the middle of the container). A conservative estimate of the pixel-to-pixel steel equivalent thickness reconstruction uncertainty as well as a model of the systematic reconstruction variation due to photon source fluctuations were applied to the simulated images so as to match the characteristics of the data images. The same dense object finding routine used for the container images, described in the previous section, was then applied to each test object image to determine the expected $r_{\rm eff}$ and $A_{\rm eff}$ of each object at practical thresholds chosen for each object. Each of these objects was simulated and analyzed under the assumption that no additional material was present in the simulated radiographs (unlike the inserted model object among benign cargo in the third panel of Figure 1), and thus the quoted sizes Table 1 are minimum estimates since the walls of the container and any other cargo present would increase the apparent size of the dense region associated with the test object in a radiograph.⁴ Thus, the results quoted for the objects represent upper bounds on the fraction of containers containing objects resembling the modeled threats.

Figure 1. (Continued)

assembled fission weapons (see Table 1). At this higher threshold, only small (~cm-scale) regions are identified, corresponding to signal noise and/or fluctuations in the uniformity of the cargo. The bottom image uses the 25.6-cm threshold, but the plutonium weapon test object (Figure C1) has been inserted into the image (accounting for saturation of the transmission, noise, etc., as described in Appendix C) and is clearly identified by the analysis. Note that the additional material of the benign cargo makes the above-threshold region of the modeled weapon appear larger, and thus easier to detect under the analysis, than it would be in isolation (as was assumed for the results presented in Tables 2). In each image, the crosses mark the total extent of each contiguous region identified by the analysis, while the circles represent the circle of the effective radius $r_{\rm eff}$. Note that regions with $r_{\rm eff}$ <2 cm are not marked for clarity and that not all pixels contained in the extent or circle of a given region are necessarily above threshold (the region must only be 4-connected).

Key results

A number of interesting results regarding the detection of nuclear and radiological threats in commercial cargo arise from this analysis. Several key distributions from the image set are presented here for discussion in the next section, while Appendix E presents further results that may be of interest to readers seeking more information regarding the material distribution inside cargo containers. For the purpose of this discussion, it is assumed that no objects that would be classified as nuclear/radiological threats were present in the analyzed images, and thus any object resembling a threat constitutes a false positive.

Figure 2 shows the distribution of the effective areal density by pixel of all containers in the image set, separated by 20- and 40-foot containers, along with the corresponding cumulative distributions. These distributions provide significantly greater detail than previously presented cargo density distributions (such as Figure 6 of Descalle et al.⁴³), which only provided average information over entire containers and thus significantly underestimated the occurrence of high areal density regions in containers that are relevant to identifying nuclear and radiological threats. Notably, a very

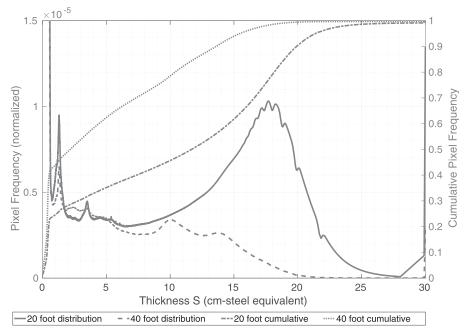


Figure 2. Distributions of the effective areal density by pixel of the cargo, separated by 20and 40-foot containers (left axis) with the corresponding cumulative distributions (right axis) in units of centimeters of steel equivalent. The peak corresponding to pixels of ≤ 0.5 -cm steel equivalent (image pixels in which no material was present between the container walls) is truncated for clarity; an untruncated version is shown in Figure E1. For these distributions, the portions of the container images including the container roofs were excluded.

small fraction of pixels (~0.001%) exceed the quoted penetration depth of the scanner (~30-cm steel equivalent), and thus there are very few contiguous regions of dense material that appear similar to the test objects. Additionally, 40-foot containers exhibit many fewer dense pixels than 20-foot containers, which follows naturally from the fact that 40-foot containers have twice the volume of 20-foot units but only ~10% higher payload capacity by weight.⁴⁴

To quantify the fraction of containers that exhibit a region consistent with the test objects, the largest contiguous region by each of the parameters $r_{\rm eff}$ and $A_{\rm eff}$ at each tested density threshold was identified for each image (since a container containing at least one object consistent with a threat would be flagged for further inspection). The fraction of 20-foot containers whose images exhibit a contiguous region above given density thresholds S larger than $r_{\rm eff}$ as a function of $r_{\rm eff}$ is presented in Figure 3. Figure 4 presents the same for the $A_{\rm eff}$ parameter.⁴⁵ The fractions of containers containing an object resembling the tests objects (at the selected density thresholds) may be immediately derived from these distributions, which amount to the false alarm rates for detection of those objects under an inspection scheme following this analysis. Table 2 presents these results.

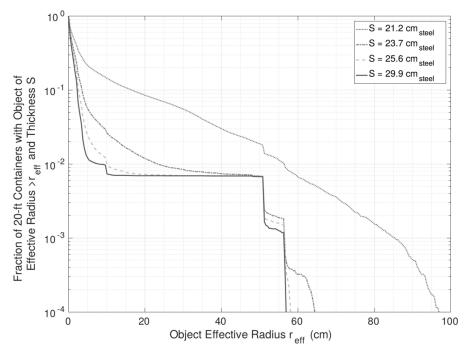


Figure 3. Fraction of 20-foot container images containing a contiguous region with effective areal density \geq S of effective radius \geq r_{eff} , for several values of S. See Figure D1 for the equivalent figure for 40-foot containers.

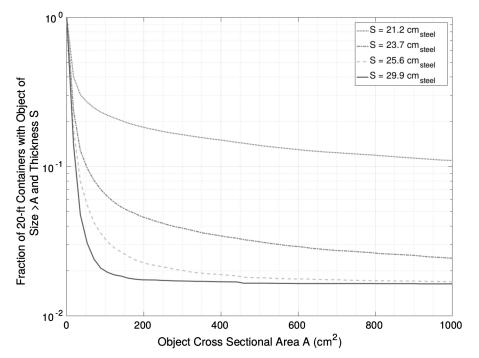


Figure 4. Fraction of 20-foot container images containing a contiguous region with effective areal density $\geq S$ of cross sectional area $\geq A_{eff}$, for several values of *S*. See Figure D2 for the equivalent figure for 40-foot containers.

Table 2. Percentage of 20-foot and 40-foot container radiographs that contain an object of at least the expected size of each of the test objects listed in Table 1 by effective radius and cross-sectional area.

Object	Threshold S	20 ft. by	20 ft. by	40 ft. by	40 ft. by
	(cm-steel)	r _{eff} (%)	A _{eff} (%)	r _{eff} (%)	A _{eff} (%)
100 cm ³ SNM	15.6	89.80	100.00	59.94	100.00
WGPu M _{crit}	21.2	40.78	39.99	10.09	10.03
HEU M _{crit}	25.6	1.49	2.51	0.87	1.68
WGPu model	25.6	1.22	2.09	0.85	1.67
HEU model	25.6	0.86	1.88	0.80	1.66
WGPu model (no tamper)	15.6	75.77	78.04	32.32	38.56
HEU model (no tamper)	23.7	4.18	12.82	0.90	2.45
3 cm Pb shell	21.2	14.94	24.80	1.06	2.13
6 cm Pb shell	25.6	0.84	1.97	0.80	1.67
9 cm Pb shell	25.6	0.76	1.73	0.80	1.63
HEU $M_{\rm crit}$ + 3 cm Pb	25.6	1.32	2.17	0.86	1.68

If it is assumed that no threatening objects of this nature were present in the cargo image data, then these percentages represent the false alarm rate for a detection regime using the method of this analysis.

Several results are immediately apparent in the Table 2 results. Each of the assembled fission devices (with tampers) are detectable by their effective size in either r_{eff} or A_{eff} at false alarm rates of $\leq 2\%$, as is the spherical near-critical mass of HEU. While the Fetter warheads represent radiographically large weapon models, this result addresses some of the most critical detection scenarios since detection of an assembled nuclear device would

necessarily be a minimum requirement of any effective inspection scheme. Similarly, a critical mass of HEU roughly represents the rough amount of material needed for a rudimentary weapon, which could be produced by a non-state actor and generally is not detectable using passive radiation monitoring in even unshielded scenarios.⁴⁶ The critical mass of WGPu as well as the model WGPu weapon without a tamper present an unacceptably high false alarm rate when searched for using this method, but due to the strong passive neutron signature of plutonium would be far more likely to be detected using existing passive monitoring if unshielded.⁴⁷ The addition of shielding or surrounding benign cargo to any of these scenarios further reduces the false alarm rate due to the additional material increasing the apparent density and object size, making it highly likely that a highly radioactive RDD could also be detected by either its passive radiation signature or the radiographic signatures of the large amount of shielding (multiple cm of lead) that would be required to mask the passive signature. Notably, however, the data show that this method alone cannot identify smaller samples of SNM, primarily due to the fact that a spherical 100 cm³ sample of SNM has a peak steel equivalent thickness of ${\sim}17\,\text{cm}$ and thus cannot be identified as a region of unexpectedly high density (and in fact appears as a very typical object given the areal density distributions shown in Figure 2).

Note that the alarm rates presented in Table 2 are somewhat conservative in that they only examine the size of the objects in the containers, while any implemented inspection scheme could utilize a number of extra pieces of information such as location in the container of the identified object, shape of the object, etc. given sufficient data describing the cargo stream. A straightforward example of this is apparent in the data: Each of the container fraction curves for the highest density thresholds tends to level off at a constant value ($\sim 0.6-1.8\%$) before dropping to near zero at a relatively large value of $r_{\rm eff}$ or $A_{\rm eff}$ (for example ~0.7% of both 20- and 40-foot containers have a largest object of high density with $r_{\rm eff} \approx 55$ cm). Examination of the cargo images reveals that these objects are elements of the container frame that the image preprocessing failed to remove and thus could be automatically disregarded in a search for threats. Such an addition to the inspection scheme could plausibly lower the false alarm rate to below 1% for the larger test objects, although the high frequency of smaller objects remains well above an acceptable alarm rate.

Implications for cargo security policy and recommended future work

This work, via the analysis of a set of 122,500 stream-of-commerce cargo container images, demonstrates that there is a significant opportunity to

improve nuclear and radiological threat detection in commercial cargo by utilizing the unique appearance of such threats in radiographs in conjunction with existing passive scanning methods. In particular, the analysis demonstrates the physical properties of certain classes of assembled model warheads, masses of SNM $\gtrsim 1$ critical mass, and shielded radiological threats sufficiently distinguish them in high-energy radiographic images from the typical contents of cargo to serve as a means of identifying possible threats with false positive rates $\leq 2\%$. Additionally, while the plutonium-based threats appear too small in the images to be distinguished from benign cargo by their radiographic appearance alone, the strong passive neutron radiation signature of such threats suggests that a detection scheme which integrates radiographic data (to search for dense shielding) and passive radiation detection data (to detect unshielded threats) could likely successfully deter a broad class of nuclear/radiological smuggling scenarios. While the relatively simple analysis presented here does not provide a complete detection scheme for all nuclear/radiological threats (especially the relatively small hollow pit models that most closely resemble modeled weapons and smaller samples of SNM), these data suggest significant value in improving the analysis of radiographic data and its integration with other data streams such as intelligence gathering and other detection methods. The facts that radiography provides significant overlap with other customs goals (e.g., detection of narcotics and stowaways) and that it is already commercially available suggest that radiography may present a more cost-effective (both financially and operationally) method of deterring at least some classes of nuclear and radiological threats in the near term than material-specific active interrogation systems. Novel active interrogation systems remain the primary focus of research efforts in this field, but this analysis suggests that there would be significant value in funding research and making data available to determine ways in which existing systems could be better used to deter nuclear and radiological threats.

Using radiography for threat detection in this manner, however, would require significant changes to deployed systems and working to increase the number of containers imaged. While approximately 5% of containers entering the United States are radiographed (having been selected based on intelligence information regarding the shipment),⁴⁸ many of these radiographs are conducted using lower-energy radioactive isotope systems such as VACIS⁴⁹ that lack sufficient penetration (such systems penetrate up to only ~17 cm-steel equivalent) to identify nuclear threats by their density.⁵⁰ This suggests that systems with penetration similar to the of the 6-MeV scanner analyzed here are necessary for identifying dense threatening

objects using the methods of this analysis. Given the extremely low frequency of cargo with density > 30-cm steel equivalent, systems with higher energies (and thus radiation dose) are likely not necessary in this context. The previous efforts in the United States to widely deploy high energy radiography systems (CAARS⁵¹) and to upgrade passive detection systems at ports failed due to a number of logistical and technical reasons,⁵² but this work suggests there may be value in revisiting the essential goals of these programs. The data suggest that approaching the nuclear/radiological threat detection problem from the standpoint of detecting either passive radiation or dense/shielded objects, rather than focusing on directly detecting nuclear materials, may provide a means of increasing the resilience of the cargo stream to nuclear/radiological threats in the nearer term. Significant questions remain regarding the fraction of containers that must be radiographed to deter smugglers in this context,⁵³ the threshold amounts of materials that must be detected, and the operational challenges associated with deploying more radiography systems in ports. This work suggests, however, that the value of radiography paired with passive detection as a nuclear/radiological threat detection tool in has perhaps been underestimated.

A lack of clear, well-motivated inspection goals has hampered research in this area, but these data provide critical information regarding the nature of materials in containers to inform future inspection requirements. Ultimately, radiography is unlikely to provide a detection solution for the small (100 cm³) samples of SNM that have been the detection goal for active interrogation system development, but these data and method of analysis suggest ways in which existing systems could be better applied while research is ongoing. Fundamentally, the conclusions from this analysis apply only to the commerce stream of the analyzed images and are subject to the assumptions of the model used to determine the system response to the test objects. Other cargo streams may contain a higher frequency of large, dense objects (e.g., a port servicing a nearby mine producing many containers filled with dense ore) and thus may contain too many objects resembling threats to use radiography in this fashion. Given the encouraging results of this analysis, however, examination of images from other cargo streams, which have not been previously made available for public and/or academic investigation, should be pursued to determine the relevance of these results for other commerce streams. Additionally, actual radiographed images of possible threatening objects should be utilized to eliminate model uncertainty, although such work may require a classified setting. While this analysis focused on identifying threats by their size and density alone, further research on data of this type would likely lead to

stronger identification algorithms. The application of machine learning techniques may be appropriate given access to sufficient training data.⁵⁴ Access to data of this type provides highly useful prior information for the development of algorithms and methods for analysis of signals for threats, not only in the context of radiography but also in the context of passive scanning by providing detailed information about the distribution of cargo materials between sources and detectors.⁵⁵ Additionally, using cargo stream data to characterize and catalog benign objects would further strengthen the capabilities of a radiography-based system to differentiate threats. As scientific and technical knowledge regarding nuclear and radiological weapons becomes more widespread, and thus available to potential smugglers, the availability of data to improve detection capabilities and assess existing and developing technologies becomes more valuable.

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Appendix

A. Modeling of the Eagle R60[®] scanner

In order to convert the 16-bit transmission images in the data set to equivalent amounts of material, and similarly to compute the expected transmission value in the Rapiscan Eagle R60[®] scanner for objects of known materials, the essential components of the radiography system were modeled: namely the bremsstrahlung beam spectrum, the physics and geometry of the transmission of the beam through containers mounted on the rail cars passing through the scanner, and the detector response to the transmitted beam as delineated by Equation (2). While not all precise details of the system were available, as some elements of the system are proprietary, a combination of published information, known performance specifications of the system, and common functionality between gamma radiography systems allows a suitable approximation of the system response to different materials (to within \sim 1 cm-steel equivalent over the full penetration range) for the purpose of the this analysis. In particular, because the transmission measurement is fundamentally a ratio between openbeam and material-in measurements under effectively the same conditions, errors in the model of the beam and detector response are second-order effects compared to the effect of the transmission physics in the materials. Each of the key elements of the model outlined by Equations (1) and (2) are described in the following sections.

Setup/geometry

The system geometry was modeled according the technical specifications from Rapiscan and⁵⁶ the additional information in Figure 7.2 of Rogers⁵⁷ and confirmed against photographs of the deployed system. Given the fact that the vertical collimation width must be comparable to the resolution of the images, and is thus a few millimeters, it may be considered negligible in modeling the system. Additionally, no significant variation in the transmission value corresponding to empty container walls was observed as a function of height in the container, and thus any effects due to the vertical "fan" spread of the beam that remained after image preprocessing were also considered as negligible. While rudimentary

models of the system were created for the Geant4⁵⁸ simulations mentioned in the following sections, no element of the geometry was critical to the ultimate analysis.

Bremsstrahlung beam

Since the precise spectrum of the gamma rays generated by the bremsstrahlung of the Rapiscan Eagle R60[®] system was not available, a simulation was conducted to produce a suitable approximation. A Geant4⁵⁹ simulation was constructed in which 6 MeV electrons (which would be produced by the linear accelerator of the radiography system) were incident on a bremsstrahlung radiator consisting of 5 mm of tungsten backed by 5 cm of copper. The spectrum of resulting gamma rays in a 1 degree vertical collimation slice forward of the beam direction was recorded and is shown in Figure A1, which was used as the representation of the beam spectrum histogram in the model (\vec{b} in Equation (2)).

Note that since this analysis only made use of transmission ratios comparing materialin-beam to the open beam transmission, and the images in the data set were preprocessed to correct for variations in the beam,⁶⁰ only the approximate shape of the spectrum was required for the analysis. In addition, only significant variations in the high-energy portion of the spectrum would be likely to significantly affect results for the transmission ratio. The uncertainty on the reconstructed material thickness was estimated from data as described later in this section, rather than using the absolute beam flux to determine precision of the transmission measurement due to variation in the number of photons detected.

Transmission modeling

The transmission component of the model (\mathcal{M} in Equation (2)), i.e., the attenuation of the beam due to materials, was modeled using a simple model of exponential attenuation and the NIST X-Ray Mass Attenuation Coefficients Database,⁶¹ which provide photon attenuation data for all elemental materials up to Z=92 and energies of 20 MeV (as well as data and prescriptions for the calculation of data for compounds of the elements). That is, for a material sample of atomic number Z, density ρ , and thickness along the beam X, the attenuation of the beam at energy E may be computed as

$$\frac{I}{I_0} = \exp\left(-\frac{\mu_Z}{\rho}X\right). \tag{A3}$$

For compound materials, the attenuation coefficient μ was calculated as⁶²

$$\frac{\mu}{\rho} = \sum_{j} \left(w_j \left(\frac{\mu}{\rho} \right)_j \right), \tag{A4}$$

where the sum runs over all elements in the compound and the weight w_j is the mass fraction of the j^{th} element. For the calculations involving plutonium, the values of $\frac{\mu}{\rho}$ for Z=94 was approximated as those of Z=92 due to the lack of available data in the NIST database. Using this model, for any material or mix of materials presented to the beam the matrix \mathcal{M} may be constructed such that $\mathcal{M}\vec{b}$ is the spectrum after the initial beam of spectrum \vec{b} passes through the material. Note that under this exponential attenuation model, in which detection of scattered beam components is neglected, \mathcal{M} is a diagonal matrix.

This model is effective for the case of the radiography system studied here due to the tight collimation of the beam. That is, photons reaching the detectors are almost exclusively photons that have undergone direct transmission, and thus secondary scattering effects that are not captured by the exponential attenuation model are not significant. This was verified by conducting

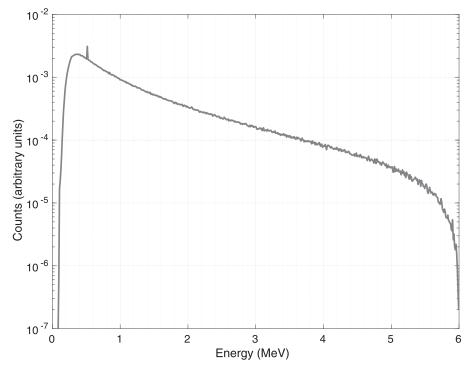


Figure A1. Simulated 6 MeV endpoint bremsstrahlung spectrum used for the radiography system model.

several Geant4⁶³ simulations of the system for different materials. The exponential transmission model differed from the Geant4 calculations by at most \sim 0.5 cm-steel equivalent, and thus the exponential model was used for computational efficiency across all materials.

Detectors

The detectors were modeled as $15.0 \times 4.6 \times 30.0$ mm CdWO₄ crystals, which are typical of those used in gamma radiography systems.⁶⁴ In a Geant4⁶⁵ simulation, photons of energies 0–6 MeV were impinged along the long axis of the crystal uniformly illuminating the central 5 mm of the second longest axis to simulate the collimated beam striking the detector crystal. The matrix \mathcal{D} mapping the initial photon energy to the distribution of resulting energy deposition in the crystal was constructed using approximately 10^7 simulated photons. Like the initial bremsstrahlung spectrum, the exact details of the detectors and their response were not available, but due to the fact that the measurement consists of a ratio and given the similarities in detectors used across bremsstrahlung radiography systems which informed the choices for the simulation the approximation used here suffices.

Conversion to steel equivalent thickness

With the transmission model in place, the transmission value T calculated for any configuration of material may be converted to an equivalent thickness of steel by determining to the calculated transmission as a function of steel thickness at standard density ($\rho_{\text{steel}} \approx 8 \text{ g/} \text{ cm}^3$). Note that as the effective atomic number of the material of a given areal density increases, the equivalent areal density of steel increases as well due to the increasing attenuation of photons in the beam due to increasing electron-positron pair production cross section as a function of Z. A lookup table as a function of material thickness was created for each relevant material, which permitted direct conversion of transmission values to equivalent steel thicknesses for each of the materials.

Uncertainty on the steel equivalent measurement

In any radiographic measurement, uncertainty on the transmission measurement (due to counting statistics and systematic effects) affects the reconstructed effective thickness for each pixel. Since the measured equivalent thickness may fluctuate downward for some of the pixels representing a given object, such fluctuations may decrease the size of the 4-connected region representing the object. Thus, in order to compare modeled objects to their representations in the radiographic images, it is necessary to estimate the effects of this reduction in the size of the 4-connected regions.

To estimate the uncertainty in the measurement of the equivalent steel thickness in the images for each pixel, a data-driven approach was used to establish an upper bound on the variance of the measurement as a function of thickness. To do this, each pixel in each image (for a subset of the entire image set in order to reduce computation time) was compared to its 4-connected neighbors, and the difference in the reconstructed equivalent thicknesses between each pixel and its neighbors was histogrammed. Under the assumption that adjacent 4-connected pixels represent very similar elements of the imaged cargo, given the ~ 0.5 cm resolution of the pixels, this provides an estimate of the measurement uncertainty but overestimates the uncertainty since adjacent pixels may in fact represent different cargo thicknesses. For each equivalent thickness in the range relevant to the image set (i.e., 0-30 cm-steel equivalent in bins of 1 cm), a Gaussian was fit to the spread of the measurements (excluding data from the T=0 bins) to determine an upper bound on the measurement uncertainty. The results of this analysis are shown in Figure A2. The combined statistical and systematic measurement uncertainty was found to be modeled well by a quadratic polynomial over the range of interest, as shown in the figure. These results were applied to simulate threatening objects in cargo as described in the following section.

Assessing the validity of the model

While this model makes a number of assumptions regarding system parameters, the model can be compared against known features of the data and available specifications of the Eagle R60[®] system to assess its validity. In particular, if the exponential attenuation model of the radiography system is valid, as has been well established for narrowly collimated bremsstrahlung radiography, then comparison to two known data points (i.e., the transmission values for known amounts of known materials) is sufficient to test the model.⁶⁶ Two such points are readily available:

• The largest peak in the pixel-by-pixel density distribution (which is shown without truncation in Figure E1) corresponds to an empty projection of a container in which the pixel represents the attenuation of the beam through just the two walls of the container and air. Due to the highly standardized nature of cargo containers, the total thickness of steel present in the two walls is a known quantity. The side walls of standard intermodal containers consist of corrugated steel plates that are 1.6 to 2.0 mm thick.⁶⁷ While the corrugation of the steel causes the amount of steel presented the beam to vary slightly along the length of the container, the average "empty pixel" represents 4.3 mm of steel (due to the diagonal portions of the corrugation increasing the

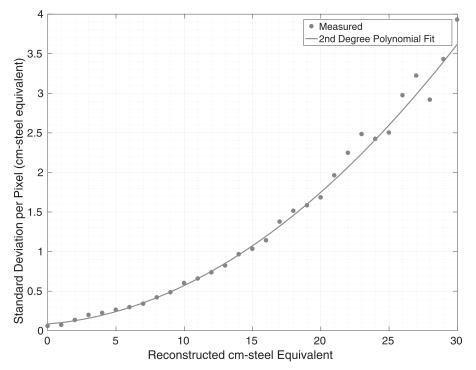


Figure A2. Uncertainty on the measured steel equivalent thickness for a single pixel as a function of equivalent steel thickness with a quadratic polynomial fit.

presented wall thickness slightly). The mean of the peak corresponding to the empty pixels in data occurs at a value of $T = 5.59 \cdot 10^4$.

• The manufacturer of the Eagle $R60^{(B)}$ quotes the steel penetration of the system, i.e., the greatest thickness of steel behind which additional material would be discernible, as 31.0 cm. Given that measurements at the low end of transmission are subject to uncertainty as discussed in the previous section, this value is slightly below the value that would correspond to a measurement of T=1 (i.e., one bit out of 2^{16}). From Figure A2, the pixel-to-pixel measurement uncertainty at 31.0-cm steel equivalent is approximately 3.8-cm steel equivalent (standard deviation). Thus, a measurement of T=1 should ideally (under a perfect measurement) corresponds to ~34.8 cm steel.

Using the model as described, the expected transmission values for each of these test cases may be computed. For 4.3 mm of steel, the model predicts $T = 5.587 \cdot 10^4$, which is in very good agreement with the data value. Note that due to the exponential nature of the attenuation, the value of T changes rapidly as a function of steel thickness for such small amounts of material, but even ± 1 mm variations in the thickness of the walls lead to changes of $\leq 3\%$ in T. Thus, the model successfully reproduces the data for the case of the empty container walls. At the low-transmission end of the data, the problem is different in that small changes in the value of T correspond to large changes in the amount of material. The model predicts that 36.4-cm steel produces a value of T=1, which corresponds to a slight overestimation but is within the uncertainty of the measurement of a single pixel. Thus, given the known data and the validity of the exponential attenuation model for the system, the model represents the data well to within O(1 cm steel) across the full range. Due to the uncertainty at the low-transmission end of the range, the comparisons between test objects and data in the text were conducted at density thresholds somewhat below the penetration limit of the system (\leq 25.6 cm steel) to reduce any possible effect from model error in this region.

B. Modeled object specifications

Table B1 presents the composition of the modeled objects listed in Table 1. Each object was modeled as concentric spherical shells (or spheres, in the case of zero inner radius) of the materials listed in the table.

C. Calculation of expected radiographed object sizes

Using the model for the measurement uncertainties described above, each of the test objects listed in Table 1 was modeled to create simulated images of the objects with the same resolution, precision, etc. as would be expected if they were imaged using the Eagle $R60^{(8)}$ system. First, each object was mapped to the 5 \times 5 mm pixel resolution of the scanner and the material composition of the object along the projection of each pixel was determined. The system model (Equations (1) and (2)) was then applied to determine the expected transmission T for each pixel, which was then converted to the steel equivalent thickness S. To determine the expected reconstructed size of each object ($r_{\rm eff}$ and $A_{\rm eff}$) given the pixel-to-pixel uncertainty derived from the data each image was simulated $\mathcal{O}(1000)$ times, applying normally distributed random fluctuations to each pixel according to the extracted standard deviation as a function of cargo thickness (Figure A2). Additionally, since some source variation was still present in the images after preprocessing,⁷² this effect was also simulated for the test object images. By examining the image set, it was determined that the remaining vertical striping artifact from the source variation amounted to an approximately 4% reduction in the reconstructed steel equivalent thickness of a given pixel in such a stripe. Since this source variation could potentially cause dense regions to be split by the vertical striping, these were conservatively simulated in test object images by applying a 10% reduction in the reconstructed thickness in the stripes and

Object	Composition (Material (Density (g/cm ³), Radial Range (cm))		
100 cm ³ SNM	HEU/WGPu (19.1, 0–2.9)		
WGPu M _{crit}	WGPu (19.8, 0–4.5)		
HEU M _{crit}	HEU (19.1, 0–8.5)		
WGPu model ⁶⁸	WGPu (19.8, 4.3–5.0) + Be (1.9, 5.0–7.0) +		
	W (19.3, 7.0–10.0) + High Explosive (1.7, 10.0–20.0) + \dots		
	AI (2.7, 20.0–21.0)		
HEU model ⁶⁹	HEU (19.0, 5.8–7.0) + Be (1.85, 7.0–9.0) +		
	W (19.3, 9.0–12.0) + High Explosive (1.7, 12.0–22.0) + \dots		
	AI (2.7, 22.0–23.0)		
WGPu model (no tamper) ⁷⁰	WGPu (19.8, 4.3–5.0) + Be (1.9, 5.0–7.0) +		
	High Explosive (1.7, 7.0–17.0) + Al (2.7, 17.0–18.0)		
HEU model (no tamper) ⁷¹	HEU (19.0, 5.8–7.0) + Be (1.85, 7.0–9.0) +		
	High Explosive (1.7, 9.0–19.0) + Al (2.7, 19.0–20.0)		
3 cm Pb shell	Pb (11.3, 8.5–11.5)		
6 cm Pb shell	Pb (11.3, 8.5–14.5)		
9 cm Pb shell	Pb (11.3, 8.5–17.5)		
HEU $M_{\rm crit}$ + 3 cm Pb	HEU (19.1, 0-8.5) + (11.3, 8.5-11.5)		

 Table B1. Modeled composition of the shielded and unshielded nuclear/radiological threats

 chosen as typical examples for this analysis listed in Table 1.

Each object was modeled as concentric spherical shells (or spheres, in the case of zero inner radius) of the materials listed in the table, with the inner and outer radius of the shell for each material listed in the table.

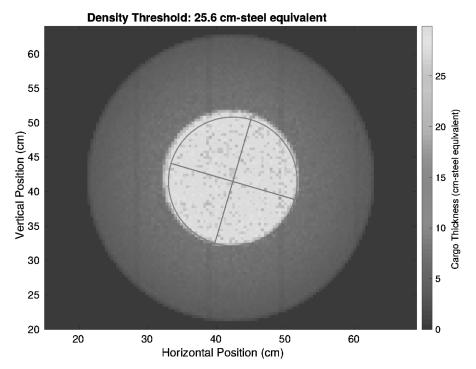


Figure C1. Simulated radiograph of the weapons-grade plutonium weapon model described in Fetter,⁷⁴ with the dense object identification algorithm applied at a threshold of 25.6-cm steel equivalent. The algorithm identifies the dense central region of the weapon above the threshold areal density (much of which is of higher areal density than the system penetration), which contains a shell of plutonium and a depleted uranium tamper, as a contiguous region of $r_{\text{eff}} = 9.6$ cm and $A_{\text{eff}} = 272$ cm² surrounded by the less dense chemical explosive material.

modeling the stripes with the maximum width observed in data. Additionally, the thickness thresholds chosen for the analysis were deliberately chosen to be less than the expected thicknesses of each object to place the thresholds well below this effect. Each of these simulated images was then processed using the same object finding algorithm as was applied to the cargo container images to compute the expected $r_{\rm eff}$ and $A_{\rm eff}$ values for the objects. For the objects of interest, it was found that the pixel-to-pixel variations led to variations of at most a few percent (except for the smallest test objects, the 100 cm³ sample and WGPu critical mass, which varied by approximately \pm 0.1 cm in radius and \pm 1 cm² in area due to statistical fluctuation), and thus the mean values of $r_{\rm eff}$ and $A_{\rm eff}$ are quoted in Table 1. Figure C1 shows the application of this procedure for the Fetter et al. plutonium weapon model⁷³ at an object detection threshold of 25.6-cm steel equivalent. The algorithm identifies the dense core of the weapon (the plutonium plus the depleted uranium tamper) with the expected effective radius and area.

D. Results for 40-foot containers

The plots presented in this section (Figures D1 and D2) present the equivalent results for 40-foot containers as are presented for 20-foot containers in Figures 3 and 4 in the main text. As noted in endnote 45, 40-foot containers contain significantly fewer large, dense

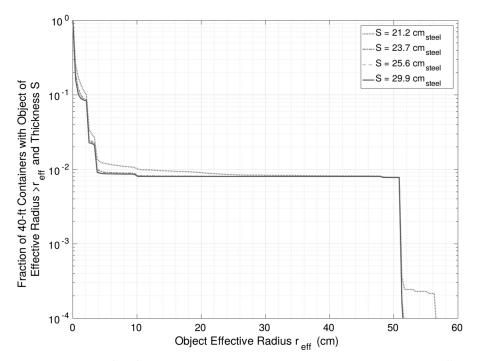


Figure D1. Fraction of 40-foot container images containing a contiguous region with effective areal density \geq S of effective radius \geq r_{eff} , for several values of S. See Figure 3 in the main article for the equivalent figure for 20 foot containers.

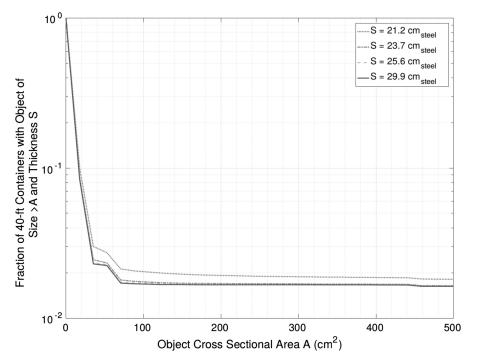


Figure D2. Fraction of 40-foot container images containing a contiguous region with effective areal density ≥ 5 of cross sectional area $\geq A_{\text{eff}}$, for several values of *S*. See Figure 4 in the main article for the equivalent figure for 20 foot containers.

108 🕒 B. S. HENDERSON

objects than 20-foot containers and thus the techniques discussed for identifying threats in the main text will perform at least as well (and in many cases significantly better) when applied to streams of 40-foot containers compared to 20-foot containers. This result follows intuitively from the fact that the weight limit for 40-foot containers is only slightly larger than the 20-foot container limit in most jurisdictions,⁷⁵ and thus 40-foot containers often contain spatially large/bulky, but not dense, shipments such as large pieces of equipment. As for the 20-foot container results shown in the main article, the data shown in this section focus on effective object thicknesses S > 20-cm steel equivalent due to the relevance of this density range to the search for objects resembling nuclear/radiological threats.

E. Additional results from the radiographic image set

This section presents several other results from the image set that do not necessarily directly pertain to the analysis presented in the main article but may be of interest to those working in the fields of cargo security and logistics. In particular, these results present information that may be useful for providing information for priors in Bayesian analyses of cargo inspection data⁷⁶ and in giving context to previous analyses of radiography for nuclear threat detection.⁷⁷ The results in this section include calculations of the average cargo areal density as a function of position in containers (Figures E6 and E7) and the distributions of the sizes of the largest objects by container that correspond to the cumulative distributions presented in the main text. Each result is described in the caption accompanying its figure, along with any notes regarding interesting features of the data.

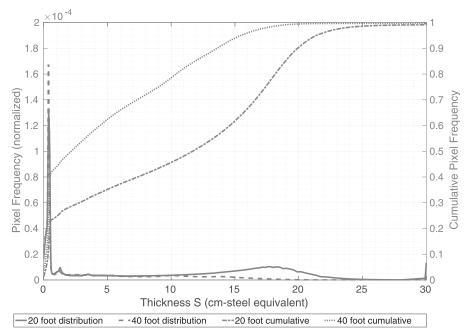


Figure E1. Distributions of the effective areal density by pixel of the cargo, separated by 20and 40-foot containers (left axis) with the corresponding cumulative distributions (right axis) in units of centimeters of steel equivalent. This figure presents the same data as Figure 2 without truncation of the *y*-axis. For these distributions, the portions of the container images including the container roofs were excluded.

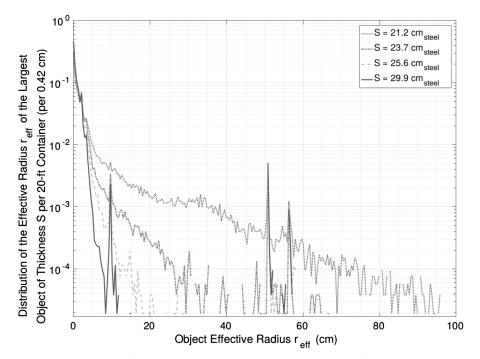


Figure E2. Distribution of the largest contiguous region by r_{eff} with effective areal density \geq S per 20-foot container, for several values of S. Figure 3 represents unity minus the cumulative distribution of this probability distribution.

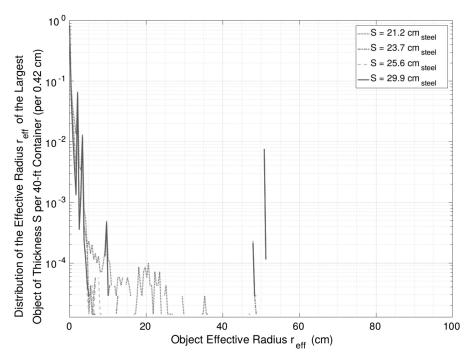


Figure E3. Distribution of the largest contiguous region by r_{eff} with effective areal density $\geq S$ per 40 foot container, for several values of *S*. Figure D1 represents unity minus the cumulative distribution of this probability distribution.

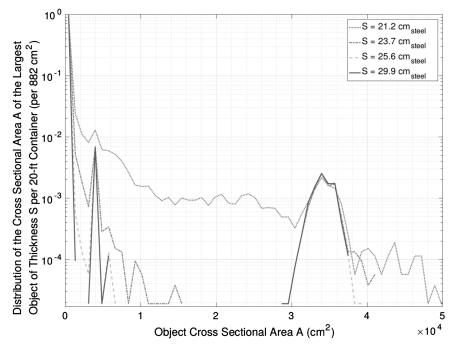


Figure E4. Distribution of the largest contiguous region by A_{eff} with effective areal density $\geq S$ per 20 foot container, for several values of *S*. Figure 4 represents unity minus the cumulative distribution of this probability distribution.

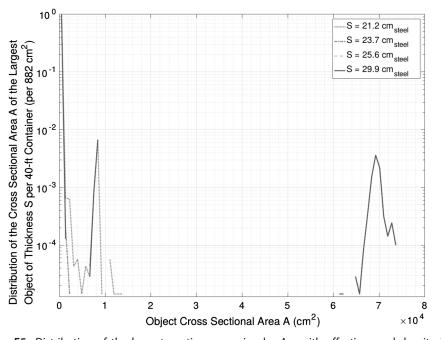


Figure E5. Distribution of the largest contiguous region by A_{eff} with effective areal density $\geq S$ per 40 foot container, for several values of *S*. Figure D2 represents unity minus the cumulative distribution of this probability distribution.

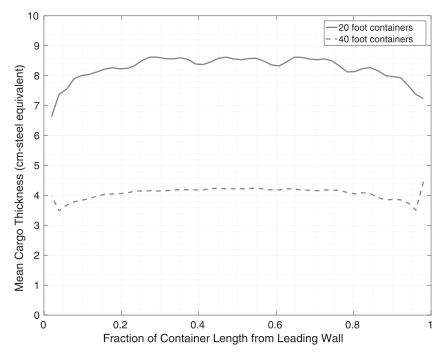


Figure E6. Mean cargo thickness in centimeters of steel equivalent as a function of position along the long axis of the containers (measured as a fraction of the distance along the container length from the leading wall) for the 20-foot and 40-foot image sets. Note the structure in the 20-foot data due to the common use of $48'' \times 48'' \times 48''$ palettes in this cargo stream, while the uniformity of the 40-foot container data indicates predominantly non-palletized cargo. In both cases, there is a slight bias toward higher densities in the central region of the containers.

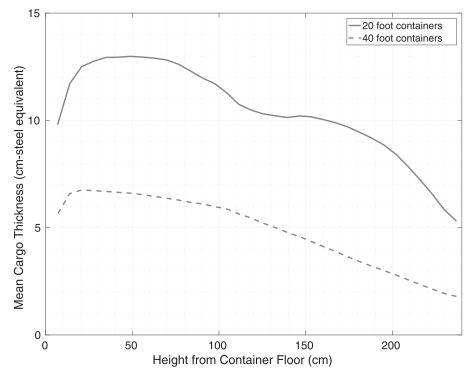


Figure E7. Mean cargo thickness in centimeters of steel equivalent as a function of height in the containers for the 20-foot and 40-foot image sets. Both sets indicate the reasonable trend of decreasing cargo density with increasing height in the container. Again, the 20-foot container data indicates stacks of two $48'' \times 48'' \times 48''$ palettes, while the 40-foot data shows no significant signs of palletized cargo. In each case, cargo is denser on average near the floors of containers as would be intuitively expected.